

# *Bar Elements*

*Gebril El-Fallah*

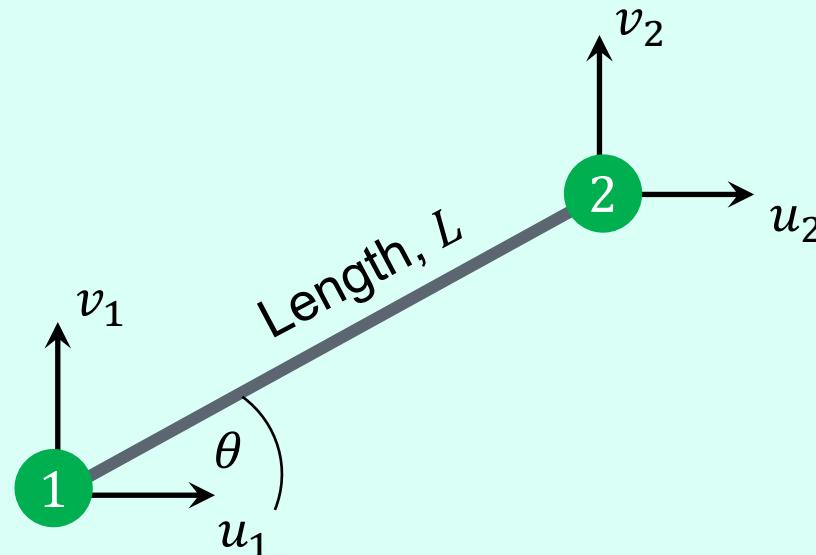
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*EG3111 – Finite Element Analysis and Design*

### 3c. Bar elements for 2D frameworks

Consider a bar element with orientation  $\theta$ . In 2D the horizontal and vertical displacements are  $u$  and  $v$ .

**DOF**



Only displacements parallel to bar axis cause extension/compression

$$\begin{array}{ccc} u_1 \cos \theta + v_1 \sin \theta & & u_2 \cos \theta + v_2 \sin \theta \\ \downarrow \rightarrow & & \downarrow \rightarrow \\ 1 & & 2 \end{array}$$

## 3c. Bar elements for 2D frameworks

### Elemental strain energy

$$U^e = \frac{1}{2} \underline{d^e}^T \cdot [\underline{k^e}] \cdot \underline{d^e}$$

$$\underline{d^e} = \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$$

$$[\underline{k^e}] = \frac{EA}{L} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$$

$$\underline{d^e} = \begin{bmatrix} u_1 \cos \theta + v_1 \sin \theta \\ u_2 \cos \theta + v_2 \sin \theta \end{bmatrix}$$

$$U^e = \frac{1}{2} [u_1 \quad u_2] \cdot \frac{EA}{L} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \cdot \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$$

$$U^e = \frac{1}{2} [u_1 \quad u_2] \cdot \frac{EA}{L} \begin{bmatrix} u_1 & -u_2 \\ -u_1 & u_2 \end{bmatrix}$$

$$U^e = \frac{1}{2} \frac{EA}{L} [u_1(u_1 - u_2) + u_2(-u_1 + u_2)]$$

$$U^e = \frac{1}{2} \frac{EA}{L} (u_2 - u_1)^2$$



### 3c. Bar elements for 2D frameworks

$$U^e = \frac{1}{2} \frac{EA}{L} (u_2 - u_1)^2$$

$$U^e = \frac{1}{2} \frac{EA}{L} (u_2 \cos \theta + v_2 \sin \theta - u_1 \cos \theta - v_1 \sin \theta)^2$$

$$U^e = \frac{1}{2} \underline{d^e}^T \cdot [k^e] \cdot \underline{d^e}$$

We wish to consider the four nodal DOF separately.

It is easy to show that  $U^e$  is the same with

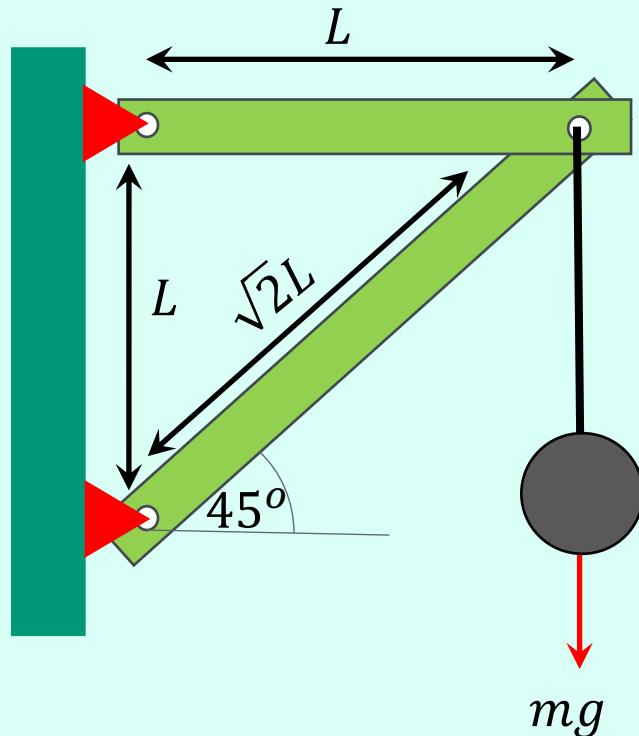
$u_1$	$v_1$	$u_2$	$v_2$
$\underline{d^e}$			

$$[k^e] = \frac{EA}{L} \begin{bmatrix} \cos^2 \theta & \cos \theta \sin \theta & -\cos^2 \theta & -\cos \theta \sin \theta \\ \cos \theta \sin \theta & \sin^2 \theta & -\cos \theta \sin \theta & -\sin^2 \theta \\ -\cos^2 \theta & -\cos \theta \sin \theta & \cos^2 \theta & \cos \theta \sin \theta \\ -\cos \theta \sin \theta & -\sin^2 \theta & \cos \theta \sin \theta & \sin^2 \theta \end{bmatrix} \begin{bmatrix} u_1 \\ v_1 \\ u_2 \\ v_2 \end{bmatrix} = \begin{bmatrix} u_1 \\ v_1 \\ u_2 \\ v_2 \end{bmatrix}$$



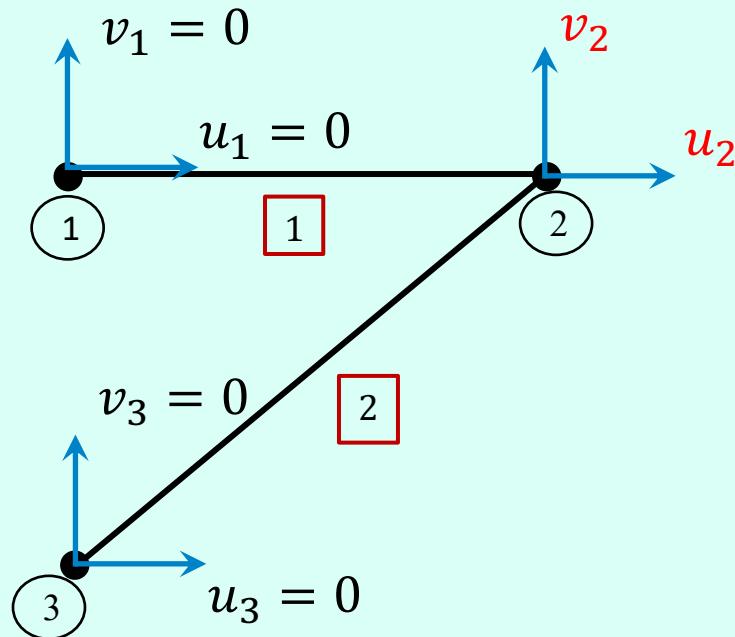
### 3c. Framework Example

Using two linear bar elements, find the unknown nodal displacements and forces, assuming  $E$  and  $A$  same for both bars

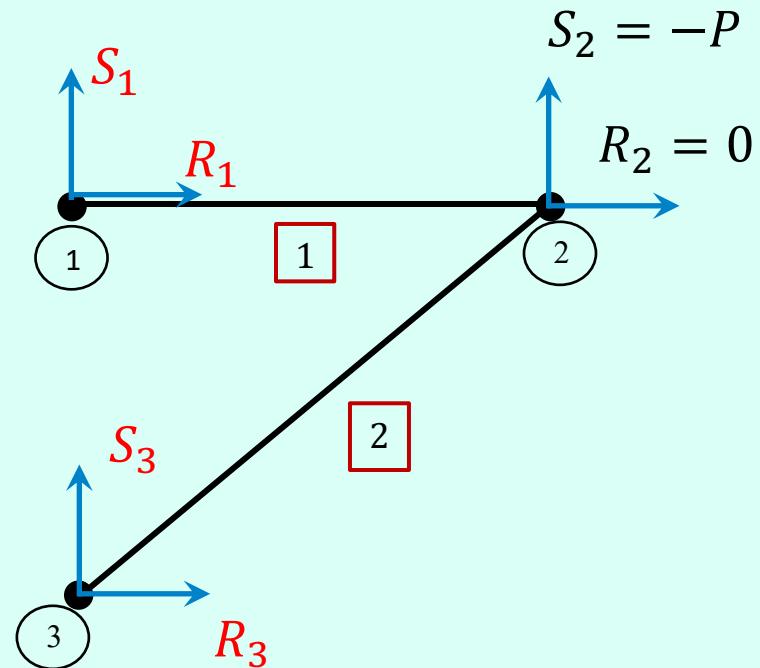


### 3c. Framework Example

**Displacements**



**Forces**



Unknown DOF in red.

$$P = mg$$

## 3c. Framework Example

*Element (1)*

$$\underline{d}^{(1)} = \begin{bmatrix} u_1 \\ v_1 \\ u_2 \\ v_2 \end{bmatrix} \quad \underline{f} = \begin{bmatrix} R_1 \\ S_1 \\ R_2 \\ S_2 \end{bmatrix}$$

**Element 1 ( $\theta = 0^\circ$ )**     $\cos^2 0^\circ = 1$     $\cos 0^\circ \sin 0^\circ = \sin^2 0^\circ = 0$

$$[k^{(1)}] = k_1 \begin{bmatrix} 1 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 \\ -1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \quad k_1 = \frac{EA}{L}$$

## 3c. Framework Example

*Element (2)*

$$\underline{d}^{(2)} = \begin{bmatrix} u_3 \\ v_3 \\ u_2 \\ v_2 \end{bmatrix} \quad \underline{f} = \begin{bmatrix} R_3 \\ S_3 \\ R_2 \\ S_2 \end{bmatrix}$$

**Element 2 ( $\theta = 45^\circ$ )**     $\cos^2 45^\circ = \cos 45^\circ \sin 45^\circ = \sin^2 45^\circ = \frac{1}{2}$

$$[k^{(2)}] = k_2 \begin{bmatrix} 1 & 1 & -1 & -1 \\ 1 & 1 & -1 & -1 \\ -1 & -1 & 1 & 1 \\ -1 & -1 & 1 & 1 \end{bmatrix} \quad k_2 = \frac{EA}{2\sqrt{2}L}$$

## 3c. Framework Example

### Assemble global matrices

$$[k^{(1)}] = k_1 \begin{bmatrix} u_1 & v_1 & u_2 & v_2 \\ 1 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 \\ -1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} u_1 \\ v_1 \\ u_2 \\ v_2 \end{bmatrix}$$

$$[k^{(2)}] = k_2 \begin{bmatrix} u_3 & v_3 & u_2 & v_2 \\ 1 & 1 & -1 & -1 \\ 1 & 1 & -1 & -1 \\ -1 & -1 & 1 & 1 \\ -1 & -1 & 1 & 1 \end{bmatrix} \begin{bmatrix} u_3 \\ v_3 \\ u_2 \\ v_2 \end{bmatrix}$$

$$k_1 = \frac{EA}{L}$$

$$k_2 = \frac{EA}{2\sqrt{2}L}$$

$$\underline{d} = \begin{bmatrix} u_1 \\ v_1 \\ u_2 \\ v_2 \\ u_3 \\ v_3 \end{bmatrix}$$

$$[K] = \begin{bmatrix} u_1 & v_1 & u_2 & v_2 & u_3 & v_3 \\ k_1 & 0 & -k_1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ -k_1 & 0 & k_1 + k_2 & k_2 & -k_2 & -k_2 \\ 0 & 0 & k_2 & k_2 & -k_2 & -k_2 \\ 0 & 0 & -k_2 & -k_2 & k_2 & k_2 \\ 0 & 0 & -k_2 & -k_2 & k_2 & k_2 \end{bmatrix} \begin{bmatrix} u_1 \\ v_1 \\ u_2 \\ v_2 \\ u_3 \\ v_3 \end{bmatrix}$$

## 3c. Framework Example

### Assemble global matrices

$$[K] = \begin{bmatrix} k_1 & 0 & -k_1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ -k_1 & 0 & k_1 + k_2 & k_2 & -k_2 & -k_2 \\ 0 & 0 & k_2 & k_2 & -k_2 & -k_2 \\ 0 & 0 & -k_2 & -k_2 & k_2 & k_2 \\ 0 & 0 & -k_2 & -k_2 & k_2 & k_2 \end{bmatrix} \quad \underline{d} = \begin{bmatrix} u_1 \\ v_1 \\ u_2 \\ v_2 \\ u_3 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ u_2 \\ v_2 \\ 0 \\ 0 \end{bmatrix}$$

$$\underline{f} = \begin{bmatrix} R_1 \\ S_1 \\ R_2 \\ S_2 \\ R_3 \\ S_3 \end{bmatrix} = \begin{bmatrix} R_1 \\ S_1 \\ 0 \\ -P \\ R_3 \\ S_3 \end{bmatrix}$$



## 3c. Framework Example

### Solution

$$[K].\underline{d} = \underline{f} \Rightarrow \begin{bmatrix} k_1 & 0 & -k_1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ -k_1 & 0 & k_1 + k_2 & k_2 & -k_2 & -k_2 \\ 0 & 0 & k_2 & k_2 & -k_2 & -k_2 \\ 0 & 0 & -k_2 & -k_2 & k_2 & k_2 \\ 0 & 0 & -k_2 & -k_2 & k_2 & k_2 \end{bmatrix} \begin{bmatrix} u_2 \\ v_2 \\ u_2 \\ v_2 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} R_1 \\ S_1 \\ 0 \\ -P \\ R_3 \\ S_3 \end{bmatrix}$$

Partition out 3<sup>rd</sup> and 4<sup>th</sup> equations where forces are known.

$$\begin{bmatrix} k_1 + k_2 & k_2 \\ k_2 & k_2 \end{bmatrix} \begin{bmatrix} u_2 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ -P \end{bmatrix}$$

## 3c. Framework Example

### Solution

$$\begin{bmatrix} u_2 \\ v_2 \end{bmatrix} = \frac{1}{(k_1 + k_2)k_2 - k_2^2} \begin{bmatrix} k_2 & -k_2 \\ -k_2 & k_1 + k_2 \end{bmatrix} \begin{bmatrix} 0 \\ -P \end{bmatrix}$$

$$\begin{bmatrix} u_2 \\ v_2 \end{bmatrix} = \frac{1}{k_1 k_2} \begin{bmatrix} k_2 P \\ -(k_1 + k_2)P \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} u_2 \\ v_2 \end{bmatrix} = P \begin{bmatrix} \frac{1}{k_1} \\ -\left(\frac{1}{k_1} + \frac{1}{k_2}\right) \end{bmatrix}$$



## 3c. Framework Example

### Solution

Substitute known displacements into remaining equations to find unknown forces.

#### Node 1

$$\begin{bmatrix} -k_1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} u_2 \\ v_2 \end{bmatrix} = \begin{bmatrix} R_1 \\ S_1 \end{bmatrix} \quad \Rightarrow \quad \begin{bmatrix} R_1 \\ S_1 \end{bmatrix} = \begin{bmatrix} -k_1 & 0 \\ 0 & 0 \end{bmatrix} \cdot P \begin{bmatrix} \frac{1}{k_1} \\ -\left(\frac{1}{k_1} + \frac{1}{k_2}\right) \end{bmatrix} = P \begin{bmatrix} -1 \\ 0 \end{bmatrix}$$

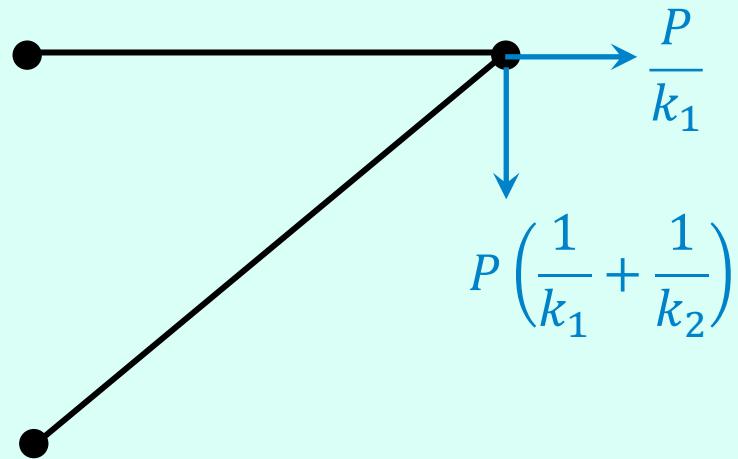
#### Node 3

$$\begin{bmatrix} -k_2 & -k_2 \\ -k_2 & -k_2 \end{bmatrix} \begin{bmatrix} u_2 \\ v_2 \end{bmatrix} = \begin{bmatrix} R_3 \\ S_3 \end{bmatrix} \quad \Rightarrow \quad \begin{bmatrix} R_3 \\ S_3 \end{bmatrix} = \begin{bmatrix} -k_2 & -k_2 \\ -k_2 & -k_2 \end{bmatrix} \cdot P \begin{bmatrix} \frac{1}{k_1} \\ -\left(\frac{1}{k_1} + \frac{1}{k_2}\right) \end{bmatrix} = P \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

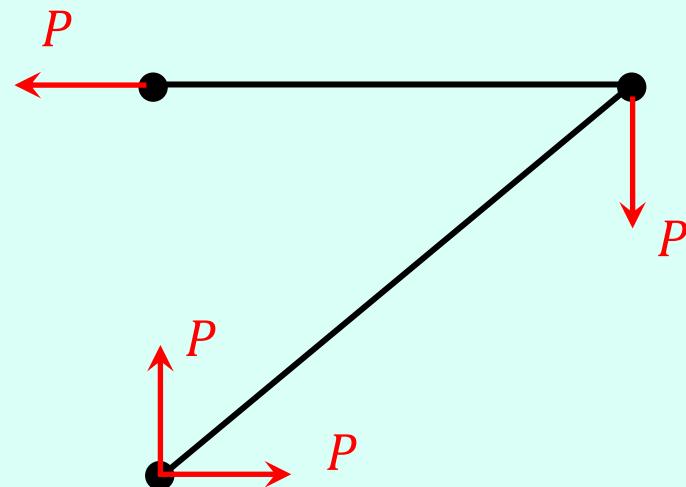


### 3c. Framework Example

#### Displacements

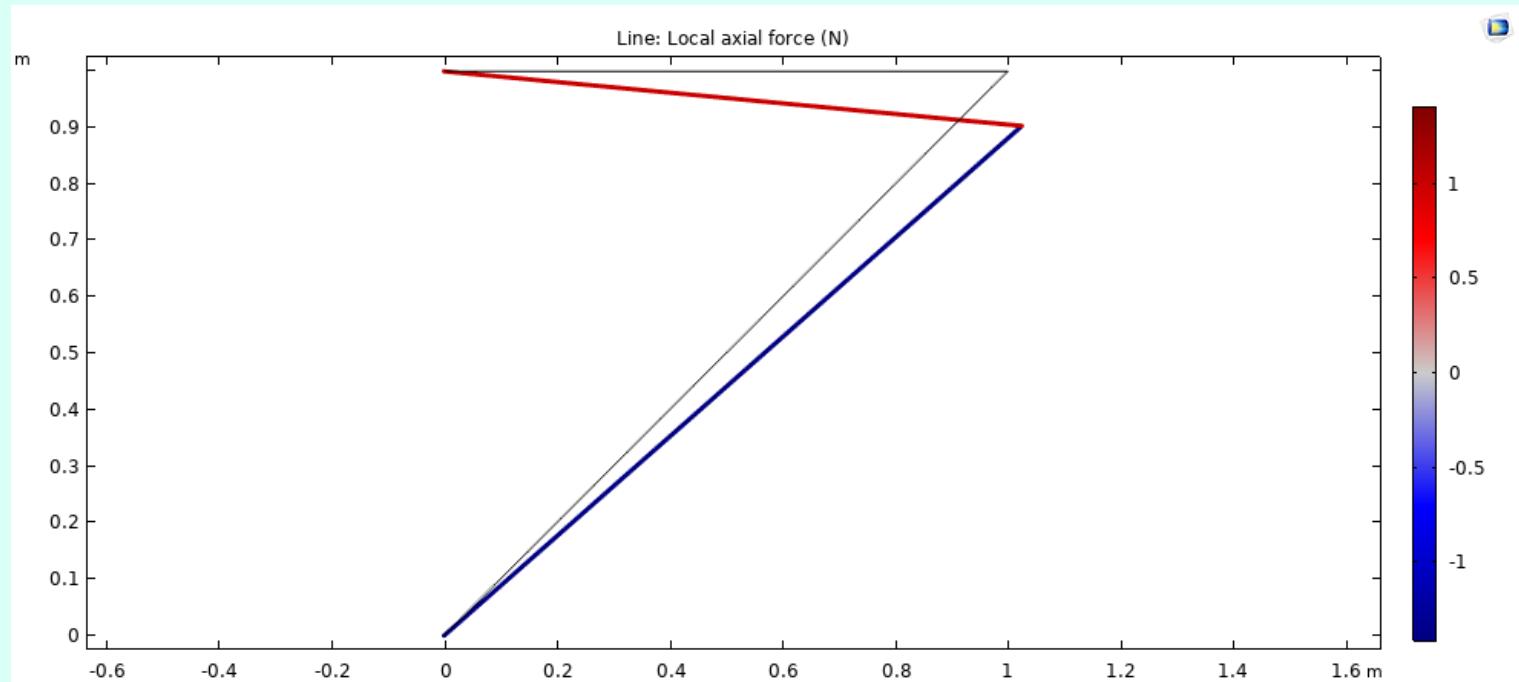


#### Forces



## 3c. COMSOL Practical #1

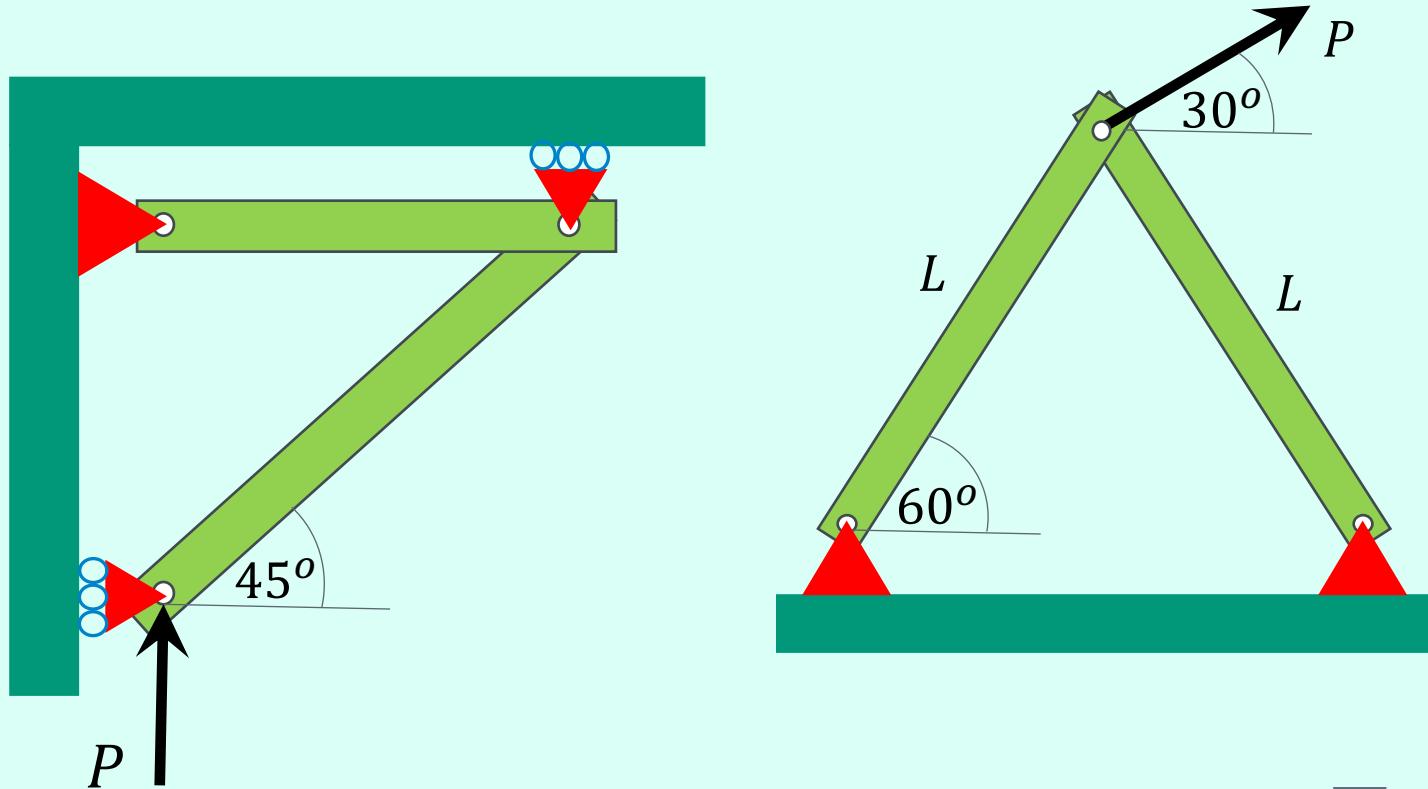
- (1) Solve this example and check solution is the same



- (1) Explore the effects of changing the angle from  $45^\circ$  using a parametric analysis.

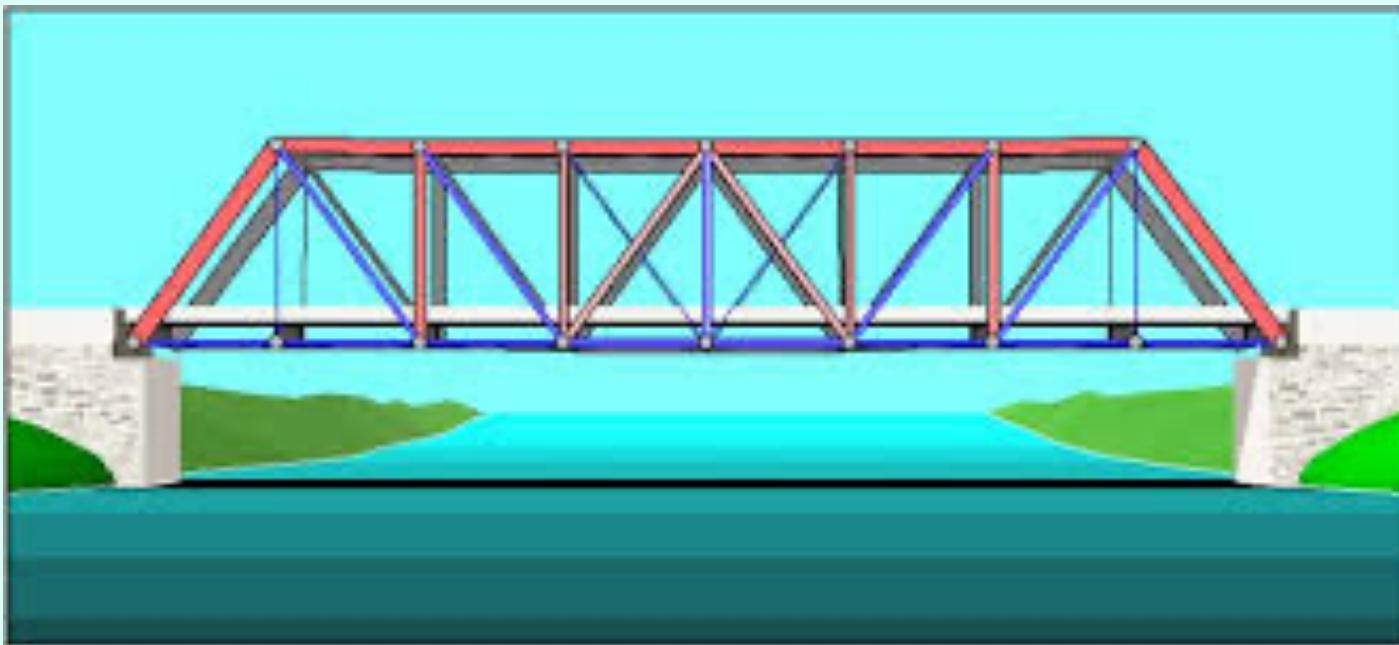
### 3c. COMSOL Practical #1 (continued)

(3) Solve the examples in **Exercise Sheet #3** and check results using COMSOL.



## 3c. COMSOL Practical #2

Design of a truss bridge



<http://blog.rasaayurveda.com>

*Next section...  
(4) Beam Elements*